

“Optimistic” Rates

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Based on work with Karthik Sridharan and Ambuj Tewari

Examples based on work with Andy Cotter, Elad Hazan, Tomer Koren,
Percy Liang, Shai Shalev-Shwartz, Ohad Shamir, Karthik Sridharan

Outline

- What?

- When?

(How?)

- Why?

Estimating the Bias of a Coin

$$|p - \hat{p}| \leq \sqrt{\frac{\log(2/\delta)}{2n}}$$

$$|p - \hat{p}| \leq \sqrt{\frac{2\textcolor{red}{p} \log(2/\delta)}{n}} + \frac{2 \log(2/\delta)}{3n}$$

Optimistic VC bound

(aka L^* -bound, multiplicative bound)

$$\hat{h} = \arg \min_{h \in \mathcal{H}} \hat{L}(h)$$

$$L^* = \inf_{h \in \mathcal{H}} L(h)$$

- For a hypothesis class with VC-dim D , w.p. $1-\delta$ over n samples:

$$L(\hat{h}) \leq L^* + \sqrt{8 \frac{D \log \frac{2en}{D} + \log \frac{2}{\delta}}{n}}$$

Optimistic VC bound (aka L^* -bound, multiplicative bound)

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- For a hypothesis class with VC-dim D , w.p. $1-\delta$ over n samples:

$$\begin{aligned} L(\hat{h}) &\leq L^* + 2\sqrt{\textcolor{red}{L}^* \frac{\textcolor{green}{D} \log \frac{2en}{D} + \log \frac{2}{\delta}}{n}} + 4 \frac{\textcolor{green}{D} \log \frac{2en}{D} + \log \frac{2}{\delta}}{n} \\ &= \inf_{\alpha} (1+\alpha)L^* + (1+\frac{1}{\alpha})4 \frac{\textcolor{green}{D} \log \frac{2en}{D} + \log \frac{2}{\delta}}{n} \end{aligned}$$

- Sample complexity to get $L(h) \leq L^* + \epsilon$:

$$n(\epsilon) = O\left(\frac{\textcolor{green}{D}}{\epsilon} \cdot \frac{\textcolor{violet}{L}^* + \epsilon}{\epsilon} \log(1/\epsilon)\right) = \tilde{O}\left(\frac{\textcolor{green}{D}}{\epsilon} \cdot \frac{\textcolor{violet}{L}^* + \epsilon}{\epsilon}\right)$$

- Extends to bounded real-valued loss, D =VC subgraph dim

From Parametric to Scale Sensitive Classes

$$L(h) = \mathbf{E}_{x,y} [\phi(h(x), y)]$$

- Instead of VC-dim or VC-subgraph-dim ($\approx$ #params), rely on metric scale to control complexity, e.g.:

$$\mathcal{H} = \{h_{\mathbf{w}} : \mathbf{w} \rightarrow \langle \mathbf{w}, \mathbf{x} \rangle \mid \|\mathbf{w}\|_2 \leq B\}$$

$$\mathcal{R}_n(\mathcal{H}) = \sqrt{\frac{\overbrace{B^2 \sup \|\mathbf{x}\|^2}^R}{n}}$$

- Learning depends on:
 - Metric complexity measures: fat shattering dimension, covering numbers, Rademacher Complexity
 - Scale sensitivity of loss ϕ (bound on derivatives or “margin”)
- For $\mathcal{H}$ with Rademacher Complexity $\mathcal{R}_n$, and $|\phi'| \leq G$:

$$L(\hat{h}) \leq L^* + 2G\mathcal{R}_n + \sqrt{\frac{\log(2/\delta)}{2n}}$$

$$\mathcal{R}_n \leq \sqrt{\frac{R}{n}}$$

$$\leq L^* + O\left(\sqrt{\frac{G^2 R + \log(2/\delta)}{n}}\right)$$

Non-Parametric Optimistic Rate for Smooth Loss

- **Theorem:** for any $\mathcal{H}$ with (worst case) Rademacher Complexity $\mathcal{R}_n(\mathcal{H})$, and any smooth loss with $|\phi''| \leq H$, $|\phi| \leq b$, w.p. $1 - \delta$ over n samples: [S Sridharan Tewari 2010]

$$L(\hat{h}) \leq \inf_{\alpha} (1+\alpha)L^* + (1+\frac{1}{\alpha})K \left(H\mathcal{R}_n^2 \log^3(n) + \frac{b \log(1/\delta)}{n} \right)$$

$\mathcal{R}_n \leq \sqrt{\frac{R}{n}}$

$$= L^* + \tilde{O} \left(\sqrt{L^* H \mathcal{R}_n} + H\mathcal{R}_n^2 \right)$$

$$= L^* + \tilde{O} \left(\sqrt{\frac{L^* H R}{n}} + \frac{H R}{n} \right)$$

- Sample complexity

$$n(\epsilon) = O \left(\frac{R}{\epsilon} \cdot \frac{L^* + \epsilon}{\epsilon} \log^3(R/\epsilon) \right) = \tilde{O} \left(\frac{R}{\epsilon} \cdot \frac{L^* + \epsilon}{\epsilon} \right)$$

Proof Ideas

- Smooth functions are self bounding: for any H -smooth non-negative f :

$$|f'(t)| \leq \sqrt{4Hf(t)}$$

- 2nd order version of Lipschitz composition Lemma, restricted to predictors with low loss:

$$\mathcal{R}_n(\mathcal{L}(r)) \leq 21\sqrt{6Hr} \log^{3/2}(64n) \mathcal{R}_n(\mathcal{H})$$

$$\mathcal{L}(r) = \left\{ (x, y) \mapsto \phi(h(x), y) \mid h \in \mathcal{H}, \hat{L}(h) \leq r \right\}$$

Rademacher $\rightarrow$ fat shattering $\rightarrow L_\infty$ covering $\rightarrow$ (compose with loss and use smoothness) $\rightarrow L_2$ covering $\rightarrow$ Rademacher

- Local Rademacher analysis

Non-Parametric Optimistic Rate for Smooth Loss

- **Theorem:** for any $\mathcal{H}$ with (worst case) Rademacher Complexity $\mathcal{R}_n(\mathcal{H})$, and any **smooth loss** with $|\phi''| \leq H$, $|\phi| \leq b$, w.p. $1 - \delta$ over n samples: [S Sridharan Tewari 2010]

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- Sample complexity

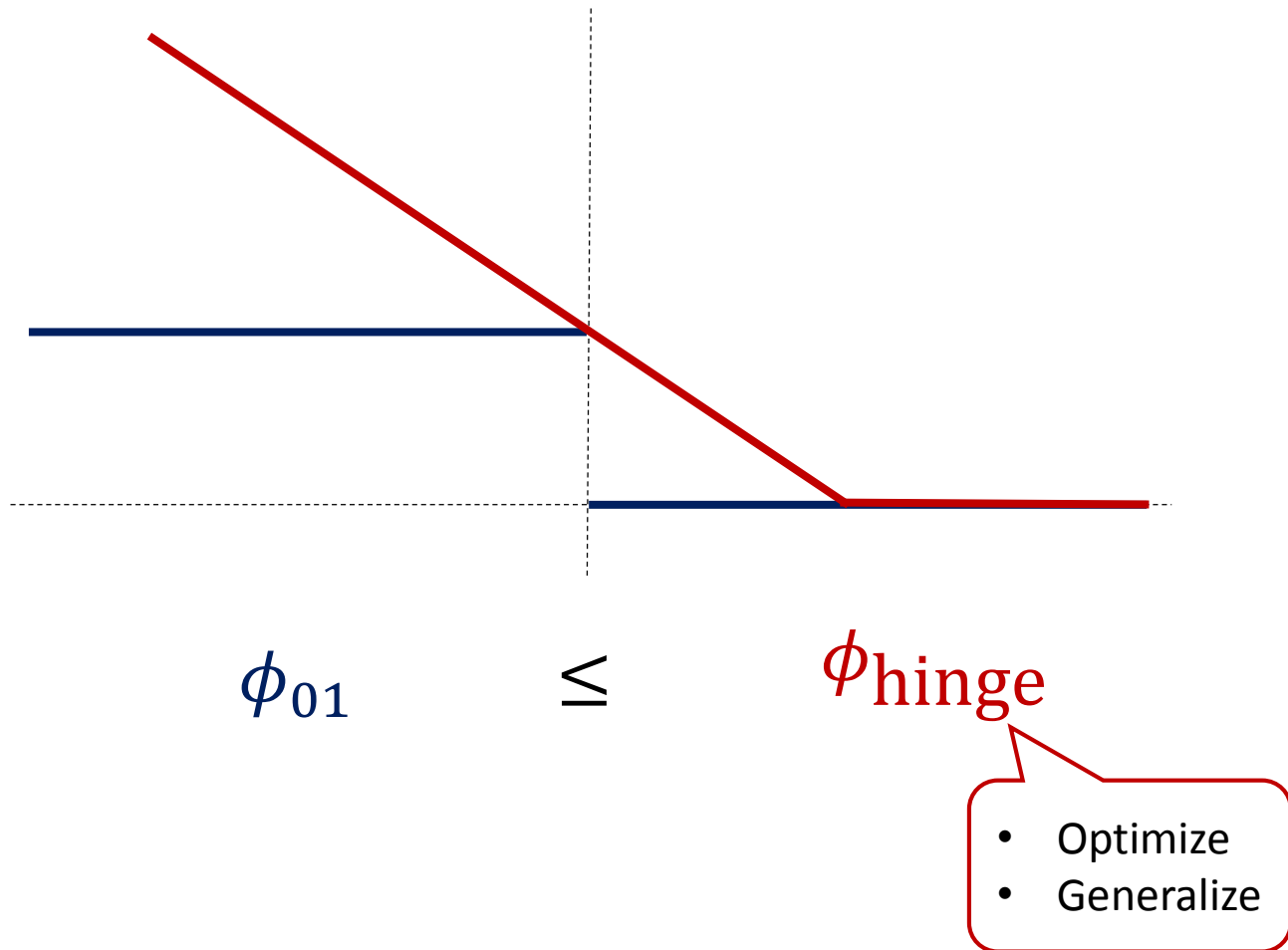
$$n(\epsilon) = O \left(\frac{R}{\epsilon} \cdot \frac{L^* + \epsilon}{\epsilon} \log^3(R/\epsilon) \right) = \tilde{O} \left(\frac{R}{\epsilon} \cdot \frac{L^* + \epsilon}{\epsilon} \right)$$

Parametric vs Non-Parametric

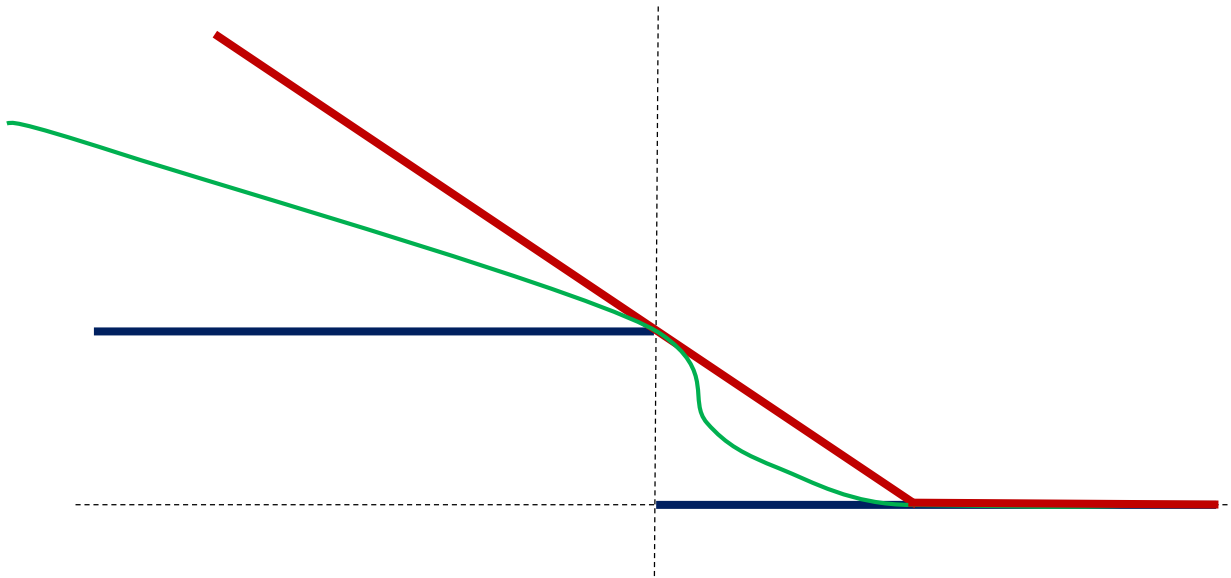
	Parametric $\dim(\mathcal{H}) \leq D, h \leq 1$	Scale-Sensitive $\mathcal{R}_n(\mathcal{H}) \leq \sqrt{R/n}$
Lipschitz: $ \phi' \leq G$ (e.g. hinge, ℓ_1)	$\frac{G D}{n} + \sqrt{L^* \frac{G D}{n}}$	$\sqrt{\frac{G^2 R}{n}}$
Smooth: $ \phi'' \leq H$ (e.g. logistic, Huber, smoothed hinge)	$\frac{H D}{n} + \sqrt{L^* \frac{H D}{n}}$	$\frac{H R}{n} + \sqrt{L^* \frac{H R}{n}}$
Smooth & strongly convex: $\lambda \leq \phi'' \leq H$ (e.g. square loss)	$\frac{H}{\lambda} \cdot \frac{H D}{n}$	$\frac{H R}{n} + \sqrt{L^* \frac{H R}{n}}$

Min-max tight up to poly-log factors

Optimistic SVM-Type Bounds



Optimistic SVM-Type Bounds



$$\phi_{01} \leq \phi_{\text{smooth}} \leq \phi_{\text{hinge}}$$

• Generalize

• Optimize

$$L_{01}(\hat{h}_{\text{hinge}}) \leq L_{\text{hinge}}^* + \tilde{O} \left(\sqrt{L_{\text{hinge}}^* \frac{R}{n}} + \frac{R}{n} \right)$$

Optimistic Learning Guarantees

$$L(\hat{h}) \leq (1 + \alpha)L^* + (1 + \frac{1}{\alpha})\tilde{O}\left(\frac{R}{n}\right)$$

$$n(\epsilon) = \tilde{O}\left(\frac{R}{\epsilon} \cdot \frac{L^* + \epsilon}{\epsilon}\right)$$

- ✓ Parametric classes
- ✓ Scale-sensitive classes with smooth loss
- ✓ SVM-type bounds
- ✓ Margin Bounds
- ✓ Online Learning/Optimization with smooth loss
- ✓ Stability-based guarantees with smooth loss
- × Non-param (scale sensitive) classes with non-smooth loss
- × Online Learning/Optimization with non-smooth loss

Why Optimistic Guarantees?

$$L(\hat{h}) \leq (1 + \alpha)L^* + (1 + \frac{1}{\alpha})\tilde{O}\left(\frac{R}{n}\right)$$

$$n(\epsilon) = \tilde{O}\left(\frac{R}{\epsilon} \cdot \frac{L^* + \epsilon}{\epsilon}\right)$$

- Optimistic regime typically relevant regime:
 - Approximation error $L^* \approx$ Estimation error ϵ
 - If $\epsilon \ll L^*$, better to spend energy on lowering approx. error (use more complex class)
- Important in understanding statistical learning

Training Kernel SVMs

Kernel evaluations to get excess error ϵ : ($R = \|w^*\|^2$)

- Using SGD:

$$T(\epsilon) = O(n(\epsilon)^2) = \tilde{O}\left(\frac{R^2}{\epsilon^2} \left(\frac{L^* + \epsilon}{\epsilon}\right)^2\right)$$

- Using the Stochastic Batch Perceptron [Cotter et al 2012]:

$$T(\epsilon) = \tilde{O}\left(\frac{R^2}{\epsilon} \left(\frac{L^* + \epsilon}{\epsilon}\right)^3\right)$$

(is this the best possible?)

Training Linear SVMs

Runtime (# feature evaluations): $(R = \|w^*\|^2)$

- Using SGD:

$$T(\epsilon) = \tilde{O}(dn(\epsilon)) = \tilde{O}\left(d \frac{R}{\epsilon} \left(\frac{L^* + \epsilon}{\epsilon}\right)\right)$$

- Using SIMBA [Hazan et al 2011]:

$$\begin{aligned} T(\epsilon) &= \tilde{O}\left((d + n(\epsilon)) \cdot R \left(\frac{L^* + \epsilon}{\epsilon}\right)^2\right) \\ &= \tilde{O}\left(dR \left(\frac{L^* + \epsilon}{\epsilon}\right)^2 + R \frac{R}{\epsilon} \left(\frac{L^* + \epsilon}{\epsilon}\right)^3\right) \end{aligned}$$

(is this the best possible?)

Mini-Batch SGD

- Stochastic optimization of smooth $L(w)$ using n training-points, doing $T=n/b$ iterations of SGD with mini-batches of size b
- Pessimistic Analysis (ignoring L^*):

$$L(\bar{w}_T) \leq O \left(\sqrt{\frac{G^2 R}{n}} + \frac{H R b}{n} \right)$$

➔ Can use minibatch of size $b \propto \sqrt{n}$, with $T \propto \sqrt{n}$ iterations and get same error (up to constant factor) as sequential SGD

[Dekel et al 2010][Agarwal Duchi 2011]

- But taking into account L^* :

$$L(\bar{w}_T) \leq O \left(\sqrt{\frac{L^* H R}{n}} + \frac{H R}{n} + \frac{H R b}{n} \right)$$

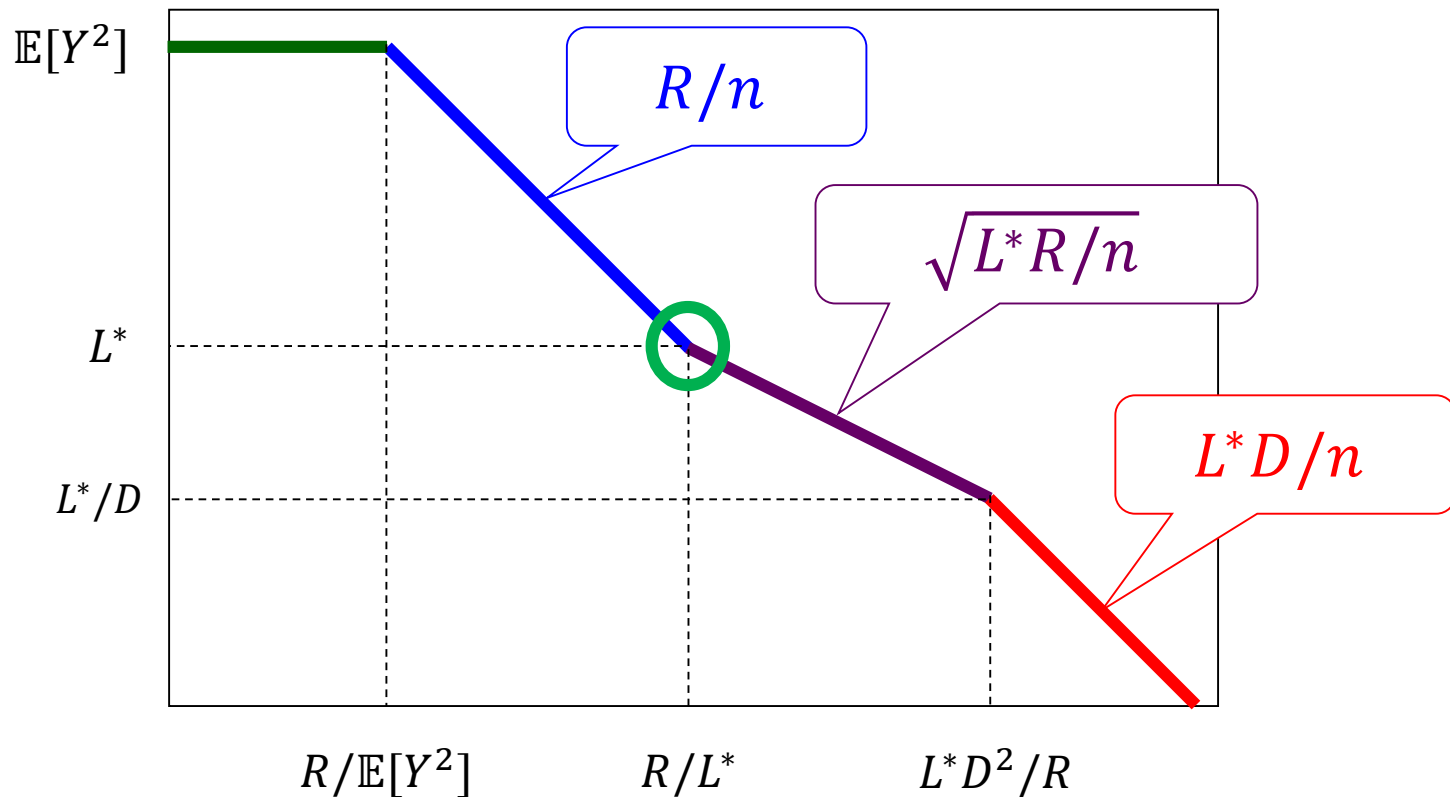
➔ In Optimistic Regime: Can't use $b > 1$, *no parallelization speedups!*

- Use acceleration to get speedup in optimistic regime 😊 [Cotter et al 2011]

Multiple Complexity Controls

[Liang Srebro 2010]

$$L(w) = \mathbb{E}[(\langle w, X \rangle - Y)^2], \quad Y = \langle w, X \rangle + \mathcal{N}(0, \sigma^2)$$
$$w \in \mathbb{R}^D \quad \|w\|^2 \leq R$$



Be Optimistic

$$n(\epsilon) = \tilde{O} \left(\frac{R}{\epsilon} \cdot \frac{L^* + \epsilon}{\epsilon} \right)$$

$$L(\hat{h}) \leq (1 + \alpha)L^* + (1 + \frac{1}{\alpha})\tilde{O} \left(\frac{R}{n} \right)$$

- For scale-sensitive non-parametric classes, with smooth loss: **[Srebro Sridharan Tewari 2010]**
 - Diff vs parametric: Not possible with non-smooth loss!
- Optimistic regime typically relevant regime:
 - Approximation error $L^* \approx$ Estimation error ϵ
 - If $\epsilon \ll L^*$, better to spend energy on lowering approx. error (use more complex class)
- Important in understanding statistical learning