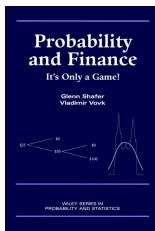


# The Design of Online Learning Algorithms



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Centrum Wiskunde & Informatica

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## Conclusion

A simple factor  $(1 + \eta r_t)$  stretches surprisingly far.

# Outline



- 1 Coin Betting
- 2 Defensive Forecasting
- 3 Squint
- 4 MetaGrad

## Coin Betting

$$\mathcal{K}_0 = 1.$$

For  $t = 1, 2, \dots$

- Skeptic picks  $M_t \in \mathbb{R}$
- Reality picks  $r_t \in [-1, 1]$
- $\mathcal{K}_t = \mathcal{K}_{t-1} + M_t r_t$

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Pick an event  $E$ .

Skeptic wins if

- 1  $\mathcal{K}_t \geq 0$
- 2  $r_1 r_2 \cdots \in E$  or  $\mathcal{K}_t \rightarrow \infty$ .

Say: Skeptic can **force**  $E$ .

## Forcing The Law of Large Numbers

Fix  $\eta \in [0, 1/2]$ . Suppose Skeptic plays  $M_t = \mathcal{K}_{t-1}\eta$ .

Then

$$\mathcal{K}_T = \mathcal{K}_{T-1} + \mathcal{K}_{T-1}\eta r_T = \mathcal{K}_{T-1}(1 + \eta r_T) = \prod_{t=1}^T (1 + \eta r_t)$$

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Now say  $C \geq \mathcal{K}_T$ . Then, using  $\ln(1+x) \geq x - x^2$ ,

$$\ln C \geq \sum_{t=1}^T \ln(1 + \eta r_t) \geq \sum_{t=1}^T \eta r_t - T\eta^2$$

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Hence

$$\frac{\ln C}{T\eta} \geq \frac{1}{T} \sum_{t=1}^T r_t - \eta \quad \text{and so} \quad \eta \geq \limsup_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T r_t$$



## Forcing The Law of Large Numbers

Finally, let Skeptic allocate a fraction  $\gamma_i$  of his initial  $\mathcal{K}_0 = 1$  to  $\eta_i$ .  
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So for each  $i$

$$\limsup_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T r_t \leq \eta_i$$

and hence

$$\limsup_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T r_t \leq 0$$

## What else

Skeptic can force many laws of probability. For example the LIL

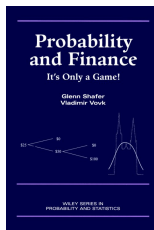
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Small deviations?



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# Experts

Let's play the experts game.

- Learner picks  $w_t \in \Delta_K$
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Goal: make sure regret compared to any expert  $k$  is **sublinear**.

$$\limsup_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T r_t^k \leq 0 \quad \text{where} \quad r_t^k = \langle w_t, \ell_t \rangle - \ell_t^k$$



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Key idea: **Defensive Forecasting**

- 1 Fix a strategy for Skeptic that forces this goal.
- 2 Play  $w_t$  so that Skeptic does not get rich

## Strategy

Strategy for Skeptic:

Split capital  $\mathcal{K}_0 = 1$  over experts  $k$  with weights  $\pi_k$  and  $\eta_i$  with  $\gamma_i$ .

$$\mathcal{K}_T = \sum_{k,i} \pi_k \gamma_i \prod_{t=1}^T (1 + \eta_i r_t^k)$$

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How to play? Make sure  $\mathcal{K}_T$  does not grow big.

$$\begin{aligned} \mathcal{K}_{T+1} - \mathcal{K}_T &= \sum_{k,i} \pi_k \gamma_i \prod_{t=1}^T (1 + \eta_i r_t^k) \eta_i r_{T+1}^k \\ &= \sum_{k,i} \pi_k \gamma_i \prod_{t=1}^T (1 + \eta_i r_t^k) \eta_i \left( \langle \mathbf{w}_{T+1}, \ell_{T+1} \rangle - \ell_{T+1}^k \right) \\ &= 0 \end{aligned}$$

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when we pick

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Needs work:

- Rates (how sublinear are the regrets?)
- Computation

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So for each  $i$  and  $k$ ,

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That is, abbreviating  $v_t^k = (r_t^k)^2$ ,

$$\sum_{t=1}^T r_t^k \leq \min_i \left( \eta_i \sum_{t=1}^T v_t^k + \frac{-\ln \pi_k - \ln \gamma_i}{\eta_i} \right)$$

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Theorem (Koolen and van Erven [2015])

$$R_T^k \leq O \left( \sqrt{V_T^k (-\ln \pi_k + \ln \ln V_T^k)} \right)$$

## Computation

$$\mathcal{K}_T = \sum_{k,i} \pi_k \gamma_i \prod_{t=1}^T (1 + \eta_i r_t^k)$$

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Indeed, we can start from **supermartingale**

$$\mathcal{K}_T \geq \Phi_T = \sum_{k,i} \pi_k \gamma_i \prod_{t=1}^T e^{\eta_i r_t^k - \eta_i^2 v_t^k} = \sum_{k,i} \pi_k \gamma_i e^{\eta_i R_T^k - \eta_i^2 V_T^k}$$

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One choice of weights to keep this small:

$$w_{T+1}^k = \frac{\sum_i \pi_k \gamma_i e^{\eta_i R_T^k - \eta_i^2 V_T^k} \eta_i}{\sum_{j,i} \pi_j \gamma_i e^{\eta_i R_T^j - \eta_i^2 V_T^j} \eta_i} \quad (\text{Squint})$$

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Maybe a continuous prior on  $\eta$  could help? How to make

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- Conjugate  $\gamma(\eta) \propto e^{-a\eta - b\eta^2}$ .  $\Rightarrow$  Truncated Gaussian mean.
- Improper  $\gamma(\eta) \propto \frac{1}{\eta}$ .  $\Rightarrow$  Gaussian CDF.



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$$R_T^k \leq O\left(\sqrt{V_T^k (-\ln \pi_k + \ln \ln T)}\right)$$

# Squint Conclusion

Computation:

- $O(1)$  time per round (like Hedge, Adapt-ML-Prod, ...)
- Library: <https://bitbucket.org/wmkoolen/squint>

Regret:

- Adaptive  $\sqrt{V_T^k (\ln K + \ln \ln T)}$  bound.
- Implies  $L^*$  bound,  $T$  bound.
- Constant regret in stochastic gap case.

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# Online Convex Optimisation

Let's play the OCO game.

For  $t = 1, 2, \dots$

- Learner plays  $\mathbf{w}_t \in \mathcal{U}$  (convex, bounded).
- Reality picks  $f_t : \mathcal{U} \rightarrow \mathbb{R}$  (convex, bounded gradient)
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Goal: small regret w.r.t. all  $\mathbf{u} \in \mathcal{U}$

$$R_T^{\mathbf{u}} = \sum_{t=1}^T (f_t(\mathbf{w}_t) - f_t(\mathbf{u}))$$

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Step 1: let's play a harder game with linearised loss

$$f_t(\mathbf{w}_t) - f_t(\mathbf{u}) \leq \langle \mathbf{w}_t - \mathbf{u}, \nabla f_t(\mathbf{w}_t) \rangle =: r_t^{\mathbf{u}}$$

## iProd/Squint for OCO

Goal: keep regret small for all  $\mathbf{u} \in \mathcal{U} \Rightarrow$  prior  $\pi$  on  $\mathbf{u}$ .

$$\mathcal{K}_T = \int_0^{1/2} \gamma(\eta) \int_{\mathcal{U}} \pi(\mathbf{u}) \prod_{t=1}^T (1 + \eta r_t^{\mathbf{u}}) d\mathbf{u} d\eta$$

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which mandates

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OCO iProd:

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Work needed:

- Picking priors
- Computation
- Rates

## Prod bound to the rescue

We might also use

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$$R_T^{\mathbf{u}} = \sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \nabla f_t(\mathbf{w}_t) \rangle$$

$$V_T^{\mathbf{u}} = \sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \nabla f_t(\mathbf{w}_t) \rangle^2$$

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linear/quadratic in  $\mathbf{u}$ .  $\Rightarrow$  suggests  $\pi(\mathbf{u})$  multivariate Normal.

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We might also use

$$\mathbf{w}_{T+1} = \frac{\int_0^{1/2} \gamma(\eta) \int_{\mathcal{U}} \pi(\mathbf{u}) e^{\eta R_T^{\mathbf{u}} - \eta^2 V_T^{\mathbf{u}}} \eta \mathbf{u} \, d\mathbf{u} \, d\eta}{\int_0^{1/2} \gamma(\eta) \int_{\mathcal{U}} \pi(\mathbf{u}) e^{\eta R_T^{\mathbf{u}} - \eta^2 V_T^{\mathbf{u}}} \eta \, d\mathbf{u} \, d\eta}$$

$$R_T^{\mathbf{u}} = \sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \nabla f_t(\mathbf{w}_t) \rangle$$

$$V_T^{\mathbf{u}} = \sum_{t=1}^T \langle \mathbf{w}_t - \mathbf{u}, \nabla f_t(\mathbf{w}_t) \rangle^2$$

linear/quadratic in  $\mathbf{u}$ .  $\Rightarrow$  suggests  $\pi(\mathbf{u})$  multivariate Normal.

But then  $\mathbf{w}_t$  may end up outside  $\mathcal{U}$ . And  $r_t^{\mathbf{u}}$  not bounded.

# MetaGrad

Let's do it anyway. Turns out it works.

$$\mathbf{w} = \frac{\sum_i \gamma_i \eta_i \mathbf{w}_i}{\sum_i \gamma_i \eta_i}$$

$$\gamma_i \leftarrow \gamma_i e^{-\eta_i r_i - \eta_i^2 r_i^2}$$

where

$$r_i = (\mathbf{w}_i - \mathbf{w})^\top \nabla f_t$$

Tilted Exponential Weights

$$\Sigma_i \leftarrow (\Sigma_i^{-1} + 2\eta_i^2 \nabla f_t \nabla f_t^\top)^{-1}$$

$$\mathbf{w}_i \leftarrow \Pi_{\mathcal{U}}(\mathbf{w}_i - \eta_i \Sigma_i \nabla f_t (1 + 2\eta_i r_i))$$

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## Theorem

*The regret of MetaGrad is bounded by*

$$R_T = O\left(\min\left\{\sqrt{T}, \sqrt{V_T^{u^*} d \ln T}\right\}\right)$$



## Consequences

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### Corollary (Koolen, Grünwald, and van Erven [2016])

For any  $\beta$ -**Bernstein**  $\mathbb{P}$ , MetaGrad keeps the expected regret below

$$\mathbb{E} R_T^* \leq O\left((d \ln T)^{\frac{1}{2-\beta}} T^{\frac{1-\beta}{2-\beta}}\right)$$

without knowing  $\beta$ .

## Conclusion

A simple factor  $(1 + \eta r_t)$  stretches surprisingly far.